

Reynolds stress The Navier-Stokes perturbation equations are: $\frac{\partial(U_i + u_i)}{\partial t} + (U_j + u_j)\frac{\partial(U_i + u_i)}{\partial x_j} = -\frac{1}{\rho}\frac{\partial(P + p)}{\partial x_i} + \nu\frac{\partial^2(U_i + u_i)}{\partial x_j^2}$ Average in time $\overline{\frac{\partial u}{\partial x_i}} = \frac{\partial \overline{u}}{\partial x_i}, \ \overline{u_i} = 0$ $\frac{\partial U_i}{\partial t} + U_j\frac{\partial U_i}{\partial x_j} + \overline{u_j}\frac{\partial u_i}{\partial x_j} = -\frac{1}{\rho}\frac{\partial P}{\partial x_i} + \nu\frac{\partial^2 U_i}{\partial x_j^2}$ Suppose that the flow is steady (i.e. $\partial/\partial t=0$), with continuity, i.e. $\partial u/\partial x=0$, and 2D flow we obtain $U_j\frac{\partial U_i}{\partial x_j} = -\frac{1}{\rho}\frac{\partial P}{\partial x_i} + \nu\frac{\partial^2 U_i}{\partial x_j^2} - \frac{\partial \overline{u_i}u_j}{\partial x_j} \xrightarrow{\text{2D}} U\frac{\partial U}{\partial x} + V\frac{\partial U}{\partial y} = -\frac{1}{\rho}\frac{\partial P}{\partial x} + \nu\frac{\partial^2 U}{\partial y^2} - \frac{\partial \overline{uv}}{\partial y}$ $U\frac{\partial U}{\partial x} + V\frac{\partial U}{\partial y} = -\frac{1}{\rho}\frac{\partial P}{\partial x} + \frac{1}{\rho}\frac{\partial}{\partial y}\left(\mu\frac{\partial U}{\partial y} - \rho\overline{uv}\right)$ The quantity $= a\overline{u}$ (in general $= a\overline{u}\overline{u}$) with used websurdeviating extended into a structure of the structure

The quantity $-\rho \overline{uv}$ (in general $-\rho \overline{u_i u_j}$) with u and v the velocity perturbations, is called the Reynolds Stress. This term is responsible for the transport of momentum from the mean flow to the perturbations.

Reynolds stress

The Reynolds stress is a mechanism of energy (or momentum) transfer from the mean flow to the perturbations. This stress is able to sustain or amplify the perturbations.

Two criteria can be explained with the transfer of momentum by the Reynolds stress:

- The Rayleigh inflection-point, and the Fjörtöft criteria.

(*Viscous effects* generally damp the perturbations... But near the boundary, they may destabilise the flow.)





Intermezzo

Squires theorem : (see Drazin & Reid 1981; Godreche et Manneville 1998). "To obtain the minimal critical Reynolds number for instability, it is sufficient to consider only two dimensional perturbations."

Use the appropriate transformation of variables.

$$\tilde{k}^{2} = k_{x}^{2} + k_{z}^{2}$$
$$\tilde{k}\hat{u} = k_{x}\hat{u} + k_{z}\hat{w}$$
$$\tilde{v} = \hat{v}$$
$$\tilde{p}/\tilde{k} = p/k_{x}$$

so that the perturbation equations become

$$i\tilde{k}\vec{u} + \frac{d\tilde{v}}{dy} = 0$$

$$i\tilde{k}[U - \tilde{c}]\tilde{u} + \frac{dU}{dy} = -ik\tilde{p}$$

$$i\tilde{k}[U - \tilde{c}]\tilde{v} = -\frac{d\tilde{p}}{dy}$$

$$\tilde{v}(y_1) = \tilde{v}(y_2) = 0$$

The perturbation equations are :

$$ik_{x} + ik_{z} + \frac{d\hat{v}}{dy} = 0$$

$$ik_{x} [U(y) - c] \hat{u} + \frac{dU}{dy} \hat{v} = ik_{x}\hat{p}$$

$$ik_{x} [U(y) - c] \hat{v} = \frac{dp}{dy}$$

$$ik_{x} [U(y) - c] \hat{w} = ik_{z}\hat{p}$$

and $c = \omega/k_x$ is the complex phase velocity. Boundary conditions are $\hat{v}(y_1) = 0$ and $\hat{v}(y_2) = 0$.

Find solutions of the dispersion relation $D(k, \omega) = 0$ in 3D!

Use Squires theorem , and transform the 3D stability problem into the equivalent 2D problem \rightarrow

Intermezzo For the 2D case, the dispersion relation is

with wavenumber \tilde{k} and $\tilde{\omega} = \tilde{k} \frac{\tilde{\omega}}{k_x} = \frac{(k_x^2 + k_z^2)^{1/2}}{k_x} \omega$, so that the 3D dispersion relation is :

$$D(\vec{k},\omega) \equiv \tilde{D}\left[(k_x^2 + k_y^2)^{1/2}, \frac{(k_x^2 + k_z^2)^{1/2}}{k_x}\omega\right] = 0$$

 $\tilde{D}(\tilde{k},\tilde{\omega})=0$

From the 2D relation for $(\tilde{k}, \tilde{\omega})$ we can obtain the properties of the 3D waves (\vec{k}, ω) . For the growth rate, ω_i , we note that

$$\frac{(k_x^2+k_z^2)^{1/2}}{k_x}\omega_i > \omega_i$$

and thus always $\omega_i(2D) > \omega_i(3D)$. For stability we can thus consider the 2D problem !

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The 2D stability problem ($\nu = 0$). Introduce the streamfunction Φ with $u = \frac{\partial \Phi}{\partial y}$ and $v = -\frac{\partial \Phi}{\partial x}$ and vorticity $\Omega = \frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} = -\nabla^2 \Phi$. Conservation of vorticity implies : $\frac{D\Omega}{Dt} = \left[\frac{\partial}{\partial t} + u.\nabla\right] \Omega = \left[\frac{\partial}{\partial t} + \frac{\partial \Phi}{\partial y}\frac{\partial}{\partial x} - \frac{\partial \Phi}{\partial x}\frac{\partial}{\partial y}\right] \nabla^2 \Phi = 0$ Perturbations : are of the form $\Phi(x, y, t) = \int U(y)dy + \psi(x, y, t)$ $\left[\frac{\partial}{\partial t} + U(y)\frac{\partial}{\partial x}\right] \nabla^2 \psi - \frac{d^2U}{dy^2}\frac{\partial \psi}{\partial x} = 0$ Normal modes : $\phi = Re\{\phi(y)e^{i(kx-\omega t)}\}$ $u = Re\{\frac{d\phi(y)}{dy}e^{i(kx-\omega t)}\}$ $v = -Re\{ik\phi(y)e^{i(kx-\omega t)}\}$ Boundary condition : $\phi(y_1) = \phi(y_2) = 0$

Explanation for stability velocity velocity velocity (a) vorticity (b) (a) (a)(... we obtain Rayleighs equation $(U - c) [\phi'' - k^2 \phi] - U'' \phi = 0$ If we suppose $U \neq c$, then

$$[\phi'' - k^2 \phi] - \frac{U''}{(U - c)} \phi = 0$$
 (1)

If ϕ is a solution, then so is its complex conjugate. Integration of (1) from y_1 to y_2 gives

$$\int_{y_1}^{y_2} (|\phi'|^2 + k^2 |\phi|^2) dy + \int_{y_1}^{y_2} \frac{U''}{(U-c)} |\phi|^2 dy = 0$$
(2)
$$\frac{U''}{U-c} |\phi|^2 = \frac{U''(U-c^*)}{|U-c|^2} |\phi|^2 = \frac{U''(U-c_r+ic_i)}{|U-c|^2} |\phi|^2$$

so that we can write for the imaginary part

$$c_i \int_{y_1}^{y_2} \frac{U''}{|U-c|^2} |\phi|^2 dy = 0$$

either stable flow $(c_i = 0)$, or instability $(c_i \neq 0)$ and $\int_{y_1}^{y_2} ... dy = 0$. For instability there must be an inflection point $U''(y) = \frac{d^2U}{dy^2} = 0$.

Fjörtöft stability criterion. (From energy conservation.) Derive the energy equation from the Euler's equations : $[\frac{\partial}{\partial t} + U(y)\frac{\partial}{\partial x}](\frac{1}{2}(u^2 + v^2 + w^2)) + \nabla [p + \frac{1}{2}(u^2 + v^2 + w^2)]\mathbf{u}$ = -U'(y)uv - U'(y)U(y)v

After taking the spatial average, i.e. integrate in wave space (x,y) from (0,0) to (λ_x, λ_y) to give

$$\frac{\partial}{\partial t}(\frac{1}{2}(\overline{u^2}+\overline{v^2}+\overline{w^2}))+\frac{\partial}{\partial y}.\overline{[p+\frac{1}{2}(u^2+v^2+w^2)v]}=-U'(y)\overline{uv}$$

With boundary conditions $v(y_1) = v(y_2) = 0$ this can be further reduced to

$$\frac{\partial}{\partial t}\int_{y_1}^{y_2}\left[\left(\frac{1}{2}(\overline{u^2}+\overline{v^2}+\overline{w^2})\right)\right]dy=-\int_{y_1}^{y_2}-U'(y)\overline{uv}dy$$

This latter relation shows the kinetic energy perturbation in response to the work done by Reynolds stress.

Fjörtöft stability criterion. Rewrite equation (2) in the form

$$\int_{y_1}^{y_2} (|\phi'|^2 + k^2 |\phi|^2) dy = -\int_{y_1}^{y_2} \frac{U''(U - c_r)}{|U - c|^2} |\phi|^2 dy$$

assume Rayleigh's criterion and add (with U_s the velocity at the inflection point)

$$(c_r - U_s) \int_{y_1}^{y_2} \frac{U''}{|U - c|^2} |\phi|^2 dy = 0$$

so that we obtain

$$\int_{y_1}^{y_2} \frac{U''(U-U_s)}{|U-c|^2} |\phi|^2 dy = -\int_{y_1}^{y_2} (|\phi'|^2 + k^2 |\phi|^2) dy < 0$$

Since the rhs is always negative, this implies for instability that

 $U''(U - U_s) 0 \le 0$ in the domain $y_1 \le y \le y_2$

For a monotonic velocity U, the absolute value of the vorticity $|\Omega(y)| \equiv |\frac{d^2 U(y)}{dy^2}|$ has then a maximum at the inflection point y_s .

Notes

- The mechanism to explain the Rayleigh inflection point theorem of shear flows, does not apply to the Fjörtöft criterion (see Orszag & Patera 1981).
- one can derive the Rayleigh criterion from conservation of momentum (see Bayly J. Fluid Mech. 1988, and Godreche & Manneville 1998). This approach shows that the Reynolds stress term plays an important role for the mechanisms of shear instability.
- The inflection point theorem works equally for bounded and unbounded flows.
- A similar approach is possible also for the Fjörtöft criterion, based on energy conservation (viscous effects are neglected).
- These are NECESSARY conditions for instability but NOT SUFFICIENT : - not all flows with inflexion point are unstable, but if the flow is unstable, then it must have an inflection point.

Counter examples are:

- U=sin (z) with inflexion points at z_s=nπ but stable flow (check Fjortoft and Rayleigh's criterion)
- Rayleigh's shear flow, i.e. U = z/b (for |z| ≤ b) with |z| ≤ lU = -l for z < -b; U=1 for z < bNo inflection point, but this flow is unstable (see course 2)





Favorable and adverse pressure gradients.

Flows over any non-flat surface may provoke an adverse or favourable pressure gradient. If there is a return flow it may generate an inflection point, so that Rayleigh's and Fjörtöft criteria apply.

The boundary layer equation is :

$$u\frac{\partial u}{\partial x} + v\frac{\partial u}{\partial y} = -\frac{1}{\rho}\frac{\partial p}{\partial x} + \nu\frac{\partial^2 u}{\partial y^2}$$

The pressure is determined by the external velocity field

$$\frac{\partial p}{\partial x} = -\rho U \frac{\partial U}{\partial x}$$

where x is along the surface of the body. At the wall we have

$$\mu \frac{\partial^2 u}{\partial v^2}|_{wall} = \frac{\partial p}{\partial x}$$

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$$\frac{1}{2}U_c'(y-y_c)^2dy + A\phi(y_c)\cos\alpha x = constant$$





Derive :

The Taylor-Goldstein equation

- ▶ Parallel flow U(z) [U + u', v', w'] and stratification N.
- Euler Equations, viscosity $\nu = 0$
- Squires theorem ($\nu = 0$) : $3D \rightarrow 2D$, stronger growth for 2D than 3D (see later)
- ▶ linearize, define a stream function $u' = \frac{\partial \psi}{\partial z}$ $w' = -\frac{\partial \psi}{\partial x}$
- perturbation $[\rho, \rho, \psi] = [\hat{\rho}(z), \hat{\rho}(z), \hat{\phi}(z)]e^{[ik(x-ct)]}$





From the exact solution (see e.g. Batchelor 1969. or Schlichting p. 116 it can be shown that $\delta{=}5~\sqrt{(vt)}$











Consider the instability for a region of just one wavelength long.
We can thus write
Kinetic energy
$$E = \frac{\rho}{2} \iint \overline{(u'^2 + v'^2)} dx dy$$
Reynolds shear stress
Work done against the
mean shear flow
$$\rho M = -\rho \lambda \iint \overline{u'v'} \frac{dU}{dy} dx dy$$

$$\mu N = \mu \iint \overline{(\zeta'^2)} dx dy$$

$$\zeta' = \frac{\partial v'}{\partial x} - \frac{\partial u'}{\partial y}$$
the mechanical balance between the redistribution of energy by the Reynolds shear
stress and the dissipation term N is:

$$\frac{\partial E}{\partial t} = \rho M - \mu N$$

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The sign of the right-hand side of this equation determines whether the energy of the disturbance increases or decreases. Large μ implies stable flow.

The ratio of the two terms can be written as

$$\rho M/_{vN} = Re M'/_N$$

 $\it Re$ the Reynolds number and M' and N' the dimensionless form of M and N

When Re M'/N' < I, i.e. when the Reynolds number is below the ratio M'/N', the disturbance will dissipate.

The least value of N'M' yields a critical Reynolds number, Re_c above which the flow will be unstable

illustration: instability of the Stokes boundary layer

Stokes boundary flow

In some cases, the viscosity in the boundary layer is capable of rendering the flow unstable. We consider the example of C.C. Lin (1955). Calculate the Reynolds stress for the vorticity equation of an oscillating boundary, of frequency ω .



Perturbations of the form $\, \sim e^{i(kx-\omega t)}$

Estimate the different advection terms inside the Stokes layer

$$\frac{\partial \zeta'}{\partial t} + U \frac{\partial \zeta'}{\partial x} + v' \frac{\partial \overline{\zeta}}{\partial y} = \nu \left(\frac{\partial^2 \zeta'}{\partial x^2} + \frac{\partial^2 \zeta'}{\partial y^2} \right)^{\text{Stokes boundary flow}}$$
Perturbations of the form $\sim e^{i(kx-\omega t)}$
Estimate the different advection terms:
Inside the Stokes layer is $\delta = \delta_0$ so that $\zeta' \approx -\partial u'/\partial y$ we obtain $\zeta' \delta_0 \sim u'$.
with continuity $du/dx + dv/dy=0$ so that $v' \sim k \, \delta_0 \, u' = k \, \delta_0^2 \, \zeta'$
Comparing the two advection terms to the time derivative:
 $\frac{U\zeta'_x}{\zeta'_t} \sim \frac{Uk\zeta'}{\omega\zeta'} \sim \frac{U}{C}$ (writing derivatives as indices,
and $C = \omega/k$, and $\zeta_y \sim U/\delta^2$)
 $\frac{v'\overline{\zeta'}y}{\zeta'_t} \sim \frac{k \delta_0^2 U \zeta'}{\omega\zeta' \delta^2} \sim \frac{U}{C} \frac{\delta_0^2}{\delta^2}$
In the boundary layer U is small $\longrightarrow U/C << 1$
both advection terms can therefore be neglected !
Since $\zeta'_{xx}/\zeta'_{yy} \sim (k\delta)^2 << I$ we consider only y dependence:
 $\frac{\partial \zeta'}{\partial t} = \nu \frac{\partial^2 \zeta'}{\partial y^2}$

$$u' = -\int_{0}^{y} \zeta' dy = -Ae^{i\theta} \int_{0}^{y} e^{\alpha y} = \frac{A}{\alpha} e^{i\theta} (1 - e^{\alpha y})$$

$$u' = -\int_{0}^{y} u'_{x} dy = -\frac{ikA}{\alpha} e^{i\theta} \int_{0}^{y} (1 - e^{\alpha y}) dy = -\frac{ikA}{\alpha} e^{i\theta} \left[y - \frac{1}{\alpha} (e^{\alpha y} - 1) \right]$$

In the boundary layer we can approximate, with $y/\delta \le l$ (and thus $ay \le l$) using Taylor expansions, we can write

$$u' \cong -\frac{A}{\alpha} e^{i\theta} \left(\alpha y + \frac{1}{2} \alpha^2 y^2 + \ldots \right) \qquad v' \cong \frac{ikA}{\alpha} e^{i\theta} \left(\frac{1}{2} \alpha^2 y^2 + \frac{1}{6} \alpha^2 y^3 + \ldots \right)$$

The Reynolds stress is defined as $\overline{u'v'}$. The time average over a period of these two sinusoidal functions can be written as ... >>>

$$\begin{split} &-\overline{u'v'} = -\frac{1}{2} \left\{ \qquad \dots \qquad \right\} = \frac{k|A|^2}{24\delta}y^4 + \dots h.o.t. \\ &-\rho \overline{u'v'} = \frac{k}{\delta} \frac{|A|^2}{24}y^4 > 0 \qquad \rightarrow \qquad M > 0 \end{split}$$

Note that u' and v' have their origin from viscous effects. For sufficiently small viscous effects, the induced shear stress will be large enough ($\rho M > \mu N$) and thus provoke instability











