Inertia-Gravity waves generated by near Balanced Flow in 2 Layer Shallow Water Turbulence on the β -Plane

Achim Wirth

MEIGE / LEGI / CNRS

EGU- Wien, April 10, 2013

◆□▶ ◆□▶ ▲□▶ ▲□▶ □ のQ@

EVALUATE: The Growl of near Balanced Flow in 2 Layer Shallow Water Turbulence on the β -Plane



Achim Wirth

MEIGE / LEGI / CNRS

EGU - Wien, April 10, 2013

▲□▶▲□▶▲□▶▲□▶ □ のQ@



Loss of Balance

(Hard) Loss of Balance by instability (Ford et al. 2000, Molemaker & McWilliams

2006)

- unstable stratification ($N^2 < 0$)
- sign change in absolut vorticity
- sign change in the difference of absolut vorticity and horizontal strain rate
- ► *Fr* > 1

Spontaneous (Soft) Loss of Balance

▶ fuzzy manifold with thickness depending on *Ro* and *Fr*.



◆□▶ ◆□▶ ▲□▶ ▲□▶ □ のので

Analogy

	Loss of Balance	Sound Emission	
ref.	Ford et al. 2000	Lighthill 1952	
hard I. of b.	Froude ≥ 1	Mach number \geq 1	
	Rossby \geq 1		
Soft I. of b.	???????	due to vorticity	
		interaction with structures	

Difference						
energy cascade	inverse	direct				
enegy dissip.	important	not important				

◆□▶ ◆□▶ ◆ □▶ ◆ □▶ ● □ ● ● ●

Phase Space

trajectory slow manifold



◆□◆▲□◆▲□◆▲□◆▲□◆

Phase Space

trajectory slow manifold



◆□ ▶ ◆□ ▶ ◆ □ ▶ ◆ □ ▶ ◆ □ ● ◆ ○ へ ○

Phase Space, Fuzzy Manifold





◆□▶ ◆□▶ ◆豆▶ ◆豆▶ □豆 − のへで

Physical model



▲□▶ ▲□▶ ▲□▶ ▲□▶ = 三 のへで

Physical Parameters

h ₁	h ₂	g	g′	f	β	Lx	Ly
600m	1400m	10 ¹ ms ⁻²	2. 10 ⁻² ms ⁻²	$10^{-4} s^{-1}$	10 ⁻¹¹ m ⁻¹ s ⁻¹	3.10 ⁶ m	3. 10 ⁶ m

Mathematical Model

2-layer Shallow-water model

Numerical Experiment

Numerical parameters : resolution 500² (15exp.), 2000² (6exp.) 4000² (1exp.)(750m). friction : $\nu = 1, 10, 100, 1000m^2s^{-1}$.

◆□▶ ◆□▶ ▲□▶ ▲□▶ □ のので

vortical motion vs. wave motion potential vorticity vs. divergence

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● のへぐ

$$q = \frac{\partial_x v - \partial_y u + f_0 + \beta y}{H + \eta} \text{ vs. } d = \partial_x u + \partial_y v$$

PV vs. Div



for film see my web-page!

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへぐ

Divergence

$$\partial_t d_1 + g \nabla^2 \eta_1 - f \zeta_1 = -\beta u_1 + \nu \nabla^2 d_1 - \partial_x (u_1 \partial_x u_1 + v_1 \partial_y u_1) - \partial_y (u_1 \partial_x v_1 + v_1 \partial_y v_1)$$

◆□▶ ◆□▶ ◆ □▶ ◆ □▶ ● □ ● ● ●

Source

inertia gravity wave = source

$$\begin{aligned} \partial_{tt}d_{1} &- gh_{1}^{0}\nabla^{2}d_{1} - gh_{2}^{0}\nabla^{2}d_{2} + f^{2}d_{1} = \\ &- \beta\partial_{t}u_{1} + \nu\partial_{t}\nabla^{2}d_{1} + \nu f\nabla^{2}\zeta_{1} \\ &- \partial_{t}\left[\partial_{x}(u_{1}\partial_{x}u_{1} + v_{1}\partial_{y}u_{1}) + \partial_{y}(u_{1}\partial_{x}v_{1} + v_{1}\partial_{y}v_{1})\right] \\ &+ g\nabla^{2}(\partial_{x}((\eta_{1} - \eta_{2})u_{1}) + \partial_{y}((\eta_{1} - \eta_{2})v_{1}) \\ &+ \partial_{x}(\eta_{2}u_{2}) + \partial_{y}(\eta_{2}v_{2}) - \kappa\nabla^{2}\eta_{1}) \\ &+ f\left[-\beta v_{1} - \partial_{x}(u_{1}\partial_{x}v_{1} + v_{1}\partial_{y}v_{1}) + \partial_{y}(u_{1}\partial_{x}u_{1} + v_{1}\partial_{y}u_{1})\right] \end{aligned}$$

Source

$$\partial_{tt}d_1 - gh_1^0 \nabla^2 d_1 - gh_2^0 \nabla^2 d_2 + f^2 d_1 = r_1$$
 (1)

if we further define the determinant and the advection operator :

$$D_i = (\partial_x u_i)(\partial_y v_i) - (\partial_x v_i)(\partial_y u_i)$$
(2)

$$A_{i} = u_{i}\partial_{x} + v_{i}\partial_{y}.$$
(3)

we get with some reordering :

$$r_{1} = -\partial_{t}(\beta u_{1} + A_{1}d_{1} + d_{1}^{2} - 2D_{1}) - f(\beta v_{1} + A_{1}\zeta_{1} + d_{1}\zeta_{1}) + g\nabla^{2}((A_{1} + d_{1})\eta_{1} + (A_{2} - A_{1} + d_{2} - d_{1})\eta_{2}) + \nu\partial_{t}\nabla^{2}d_{1} + \nu f\nabla^{2}\zeta_{1} - \kappa g\nabla^{4}\eta_{1}$$
(4)

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● のへで



ΡV

▲□ → ▲□ → ▲目 → ▲目 → ● ● ● ● ●

Divergence



▶ ▲ 臣 ▶ ▲ 臣 ▶ ▲ 臣 → � � �

Scale







・ロト・日本・モート ヨー うへの



◆□> <圖> < E> < E> < E < のへの</p>



◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへぐ

Conclusions

- No strong loss of balance in the enstrophy cascade (no barking) although strong fronts and eddies are observed.
- Dynamics stays close to balance even when small scales appear.
- Faint continuous gravity wave generation (growl), showing the existence of a fuzzy manifold.

Question

How does the system manage to keep balance at small scales? (By avoiding fast motion?)

Perspectives

 Look at cascades of inertia-gravity wave turbulence (weak and strong).